Definition

Convolution

Definition 9. Let f(t) and g(t) be piecewise continuous on $[0, \infty)$. The convolution of f(t) and g(t), denoted f * g, is defined by

(3)
$$(f * g)(t) \coloneqq \int_0^t f(t - v)g(v) dv.$$

<u>Ex 0</u>: Calculate $t^2 * t^3$

Properties of Convolution

Properties of Convolution

Theorem 10. Let f(t), g(t), and h(t) be piecewise continuous on $[0, \infty)$. Then

- (4) f*g = g*f,
- (5) f*(g+h) = (f*g) + (f*h),

(6)
$$(f * g) * h = f * (g * h),$$

(7) f * 0 = 0.

<u>Proof of (5)</u>:

Convolution Theorem

Convolution Theorem

Theorem 11. Let f(t) and g(t) be piecewise continuous on $[0, \infty)$ and of exponential order α and set $F(s) = \mathcal{L}{f}(s)$ and $G(s) = \mathcal{L}{g}(s)$. Then

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(8) \mathscr{L}{f*g}(s) = F(s)G(s),
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or, equivalently,

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(9) \mathscr{L}^{-1}{F(s)G(s)}(t) = (f * g)(t).
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Convolution Theorem

(8) $\mathscr{L}{f*g}(s) = F(s)G(s)$

Proof:

Convolution Theorem

Example 1 Use the convolution theorem to solve the initial value problem

(11) y'' - y = g(t); y(0) = 1, y'(0) = 1,

where g(t) is piecewise continuous on $[0, \infty)$ and of exponential order.

Convolution Theorem

Example 2 Use the convolution theorem to find $\mathscr{L}^{-1}\{1/(s^2+1)^2\}$.

Convolution Theorem

Example 3 Solve the integro-differential equation

(12)
$$y'(t) = 1 - \int_0^t y(t-v)e^{-2v}dv$$
, $y(0) = 1$.

<u>Goal</u>: Solve the IVP ay'' + by' + cy = g; $y(0) = y_0$, $y'(0) = y_1$ and writing the answer as a convolution <u>Step 1</u>: Solve the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 using the impulse response function

1) The transfer function H(s) of a linear system is defined as the ratio of the Laplace transform of the output function y(t) to the Laplace transform of the input function g(t), under the assumption that all initial conditions are zero. That is, H(s) = Y(s)/G(s).

<u>Goal</u>: Solve the IVP ay'' + by' + cy = g; $y(0) = y_0$, $y'(0) = y_1$ and writing the answer as a convolution <u>Step 1</u>: Solve the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 using the impulse response function

i) For this IVP, the transfer function is $H(s) = \frac{1}{as^2+bs+c}$

ii) The function $h(t) \coloneqq \mathscr{L}^{-1}{H}(t)$ is called the **impulse response function** for the system because, physically speaking, it describes the solution when a mass–spring system is struck by a hammer (see Section 7.9). We can also characterize h(t) as the unique solution to the homogeneous problem

(16) ah'' + bh' + ch = 0; h(0) = 0, h'(0) = 1/a.

<u>Goal</u>: Solve the IVP ay'' + by' + cy = g; $y(0) = y_0$, $y'(0) = y_1$ and writing the answer as a convolution <u>Step 1</u>: Solve the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 using the impulse response function

i) For this IVP, the transfer function is $H(s) = \frac{1}{as^2+bs+c}$

ii) Find the impulse response function h(t) by either calculating $\mathcal{L}^{-1}{H(s)}$ or solving the IVP $ah'' + bh' + ch = 0; \quad h(0) = 0, \quad h''(0) = \frac{1}{a}$

iii) Then the solution to the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 is (h * g)(t)

<u>Goal</u>: Solve the IVP ay'' + by' + cy = g; $y(0) = y_0$, $y'(0) = y_1$ and writing the answer as a convolution <u>Step 1</u>: Solve the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 using the impulse response function

iii) Then the solution to the IVP ay'' + by' + cy = g; y(0) = 0, y'(0) = 0 is (h * g)(t)

<u>Step 2</u>: Solve the IVP ay'' + by' + cy = 0; $y(0) = y_0$, $y'(0) = y_1$ call the solution y_k (2nd order homogeneous linear equation section 4.2-4.3 stuff)

Step 3: Then the solution to the IVP ay'' + by' + cy = g; $y(0) = y_0, y'(0) = y_1$ is $y(t) = (h * g)(t) + y_k(t)$

Solution Using Impulse Response Function

Theorem 12. Let *I* be an interval containing the origin. The unique solution to the initial value problem

$$ay'' + by' + cy = g;$$
 $y(0) = y_0,$ $y'(0) = y_1,$

where a, b, and c are constants and g is continuous on I, is given by

(20)
$$y(t) = (h * g)(t) + y_k(t) = \int_0^t h(t - v)g(v)dv + y_k(t)$$
,

where h is the impulse response function for the system and y_k is the unique solution to (19).

Example 4 A linear system is governed by the differential equation

(21) y'' + 2y' + 5y = g(t); y(0) = 2, y'(0) = -2.

Find the transfer function for the system, the impulse response function, and a formula for the solution.